

AC2-5 INSTRUCTION FOR USE

Thank you for having chosen a LAE electronic product. Before installing the instrument, please read these instructions carefully to ensure maximum performance and safety.

DESCRIPTION



Fig.1 - Front panel

INDICATION

- 1 = Channel 1 output
- 2 = Channel 2 output
- °C/°F = View in °C or °F
- = Alarm
- = Tap
- = Hold

INSTALLATION

- Insert the controller through a hole measuring 71x29 mm;
- Make sure that electrical connections comply with the paragraph "wiring diagrams". To reduce the effects of electromagnetic disturbance, keep the sensor and signal cables well separate from the power wires.
- Fix the controller to the panel by means of the suitable clips, by pressing gently; if fitted, check that the rubber gasket adheres to the panel perfectly, in order to prevent debris and moisture infiltration to the back of the instrument.
- ATTENTION: during the setup of the controller, please make sure that the parameter INP matches the sensor used, as indicated in the table "input specifications".
- Place the probe T1 inside the room in a point that truly represents the temperature of the stored product.

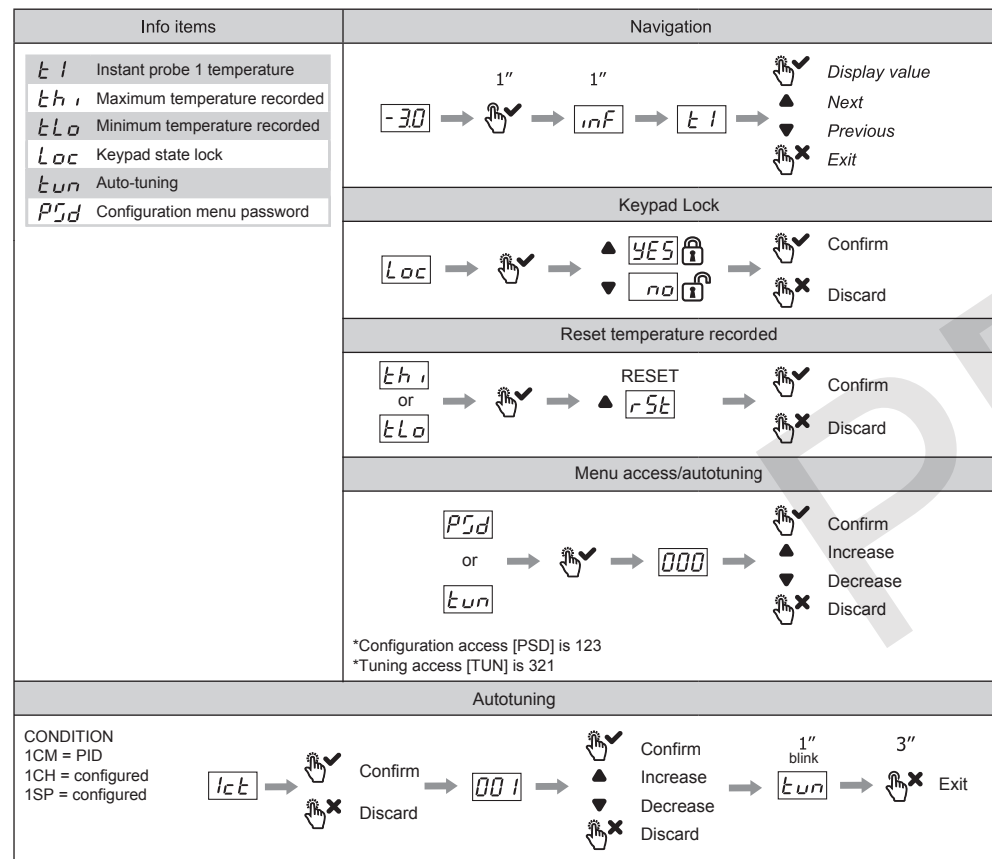
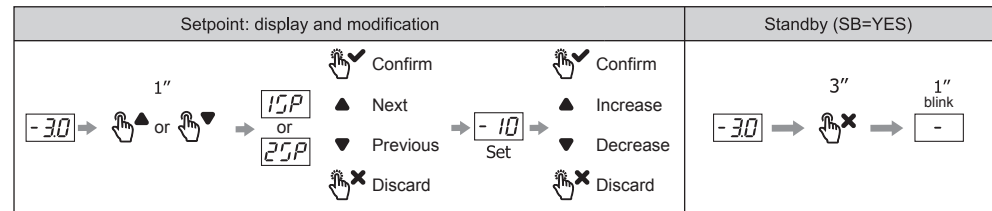
OPERATION

DISPLAY

During normal operation, the display shows either the temperature measured or one of the following indications:

-	Controller in stand-by	ALr	Digital input alarm
or	Probe T1 overrange or failure	E1	In tuning: timeout1 error
h	Room high temperature alarm	E2	In tuning: timeout2 error
Lo	Room low temperature alarm	E3	In tuning: overrange error
hc	Condenser high temperature	tun xx.x	Controller in autotuning

SETTING



Errors

- E1 timeout1 error: the controller could not bring the temperature within the proportional band. Increase 1SP in case of heating control, vice versa, decrease 1SP in case of refrigerating control and re-start the process.
- E2 timeout2 error: the autotuning has not ended within the maximum time allowed (1000 cycle times). Re-start the autotuning process and set a longer cycle time 1CT.
- E3 temperature overrange: check that the error was not caused by a probe malfunction, then decrease 1SP in case of heating control, vice versa increase 1SP in case of refrigerating control and then re-start the process.

- To eliminate the error indication and return to the normal mode, press button **x**.
- Control improvement**
- To reduce overshoot, reduce the integral action reset **1AR**
- To increase the response speed of the system, reduce the proportional band **1PB**. Caution: doing this makes the system less stable.
- To reduce swings in steady-state temperature, increase the integral action time **1IT**; system stability is thus increased, although its response speed is decreased.
- To increase the speed of response to the variations in temperature, increase the derivative action time **1DT**. Caution: a high value makes the system sensitive to small variations and it may be a source of instability.

CONFIGURATION PARAMETERS

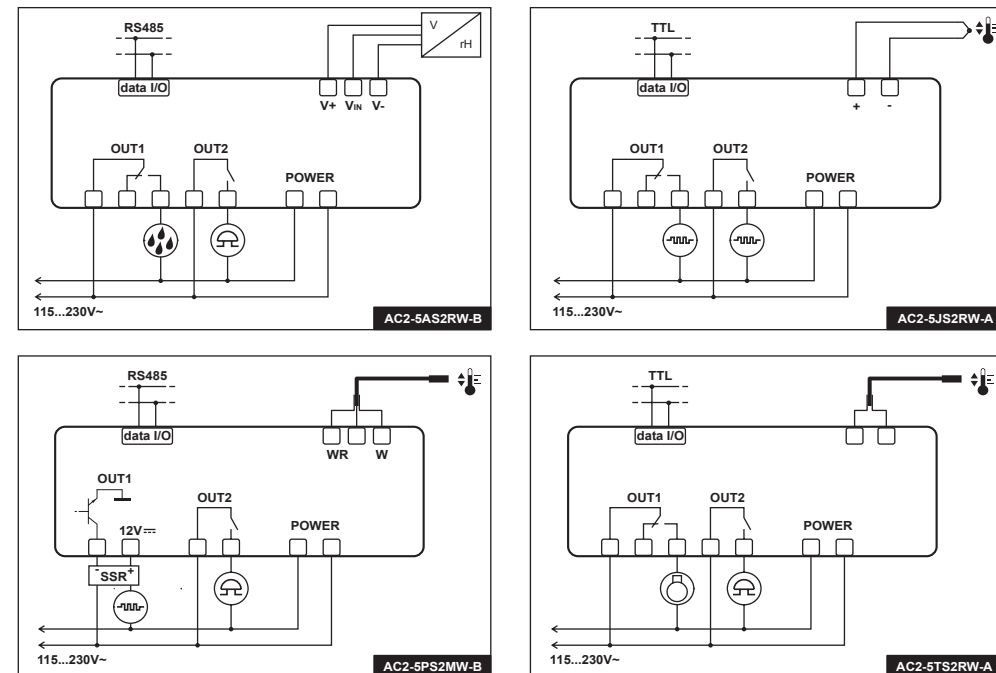
PAR	RANGE	DESCRIPTION
SCL	1°C; 2°C; °F	Readout scale (see table of input specifications) Caution: upon changing the SCL value, it is then <u>absolutely necessary to reconfigure the parameters relevant to the absolute and relative temperatures (SPL, SPH, 1SP, 1HY etc.)</u>
SPL	-50...SPH	Minimum limit for 1SP setting
SPH	SPL...150°	Maximum limit for 1SP setting.
1SP	SPL... SPH	Setpoint (value to be maintained in the room).
1CM	HY; PID	Control mode. With 1CM=HY you select control with hysteresis: parameters 1HY, 1T0 and 1T1 are used. With 1CM=PID you select a Proportional-Integral-Derivative control mode: parameters 1PB, 1IT, 1DT, 1AR, 1CT will be used
1CH	REF; HEA	Refrigerating (REF) or Heating (HEA) control mode.
1CM=HY	1HY	0...19.9° OFF/ON thermostat differential. With 1HY=0 the output is always off.
	1T0	0...30min Minimum off time. After output 1 has been turned off, it remains inactive for 1T0 minutes regardless of the temperature value measured.
	1T1	0...30min Minimum on time. (the following parameter will be 1PF). After output 1 has been turned on, it remains active for 1T1 minutes regardless of the temperature value measured.
1CM=PID	1PB	0...19.9° Proportional bandwidth. Temperature control takes place by changing the ON time of the output: the closer the temperature to the setpoint, the less time of activation. A small proportional band increases the promptness of response of the system to temperature variations, but tends to make it less stable. A purely proportional control stabilises the temperature within the proportional band but does not cancel the deviation from setpoint. With 1PB=0 the output is always off.
	1IT	0...999s Integral action time. The steady-state error is cancelled by inserting an integral action. The integral action time, determines the speed with which the steady-state temperature is achieved, but a high speed (1IT low) may be the cause of overshoot and instability in the response. With 1IT=0 the integral control is disabled.
	1DT	0...999s Derivative action time. Response overshoot may be reduced by inserting a derivative Action. A high derivative action (1DT high) makes the system very sensitive to small temperature variations and causes instability. With 1DT=0 the derivative control is disabled.
1CM=HY	1AR	0...100% Reset of integral action time referred to 1PB Decreasing the parameter 1AR reduces the integral control action zone, and consequently the overshoot (see figure on paragraph 1IT).
	1CT	1...255s Cycle time. It's the period in which the output ON time changes. The quicker the system to be controlled reacts to temperature variations, the smaller the cycle time must be, in order to obtain higher temperature stability and less sensitivity to load variations.
	1PF	ON/OFF Output state in case of probe failure.
OAU	NON; THR; AL0; AL1	AUX output operation. NON: output disabled (always off). (the next parameter will be ATM) THR: output programmed for second thermostat control (the next parameter will be 2SM). AL0: contacts open when an alarm condition occurs (the next parameter will be ATM). AL1: contacts make when an alarm condition occurs (the next parameter will be ATM).
2SM	2SM	ABS; REL Setpoint 2 mode. Channel 2 setpoint may be absolute (2SM=ABS), or a differential relative to setpoint 1 (2SM=REL)
	2SP	SPL...SPH Auxiliary output switchover temperature (the next parameter will be 2CH)
2DF	2DF	-19.9...19.9° Temperature differential relative to 1SP. The auxiliary output setpoint is equal to 1SP+2DF

OAU=THR	2CH	REF; HEA	Refrigerating control (REF) or heating control mode (HEA) for the auxiliary output.
	2HY	0...19.9°	Differential of thermostat 2. With 2HY=0 the auxiliary output always remains off.
	2T0	0...30min	Minimum off time. After output 2 has been turned off, it remains inactive for 2T0 minutes regardless of the temperature value measured.
	2T1	0...30min	Minimum on time. After output 2 has been turned on, it remains active for 2T1 minutes regardless of the temperature value measured.
2PF	2PF	ON/OFF	Auxiliary output state in case of probe failure.
	ATM	NON; ABS; REL	Alarm threshold management. NON: all temperature alarms are inhibited (the following parameter will be SB). ABS: the values programmed in ALA and AHA represent the real alarm thresholds. REL: the values programmed in ALR and AHR are alarm differentials referred to 1SP and 1SP+1HY.
ATM=ABS	ALA	-50...AHA	Low temperature alarm threshold.
	AHA	ALA...150°	High temperature alarm threshold.
	ALR	-12.0...0°	Low temperature alarm differential. With ALR=0 the low temperature alarm is excluded
ATM=REL	AHR	0...12.0°	High temperature alarm differential. With AHR=0 the high temperature alarm is excluded
	ATD	0...120min	Delay before alarm temperature warning.
SB	NO/YES	Stand-by button enabling.	
INP	0mA/4mA, T1/T2, ST1/SN4	Sensor input selection (see table of input specifications). In the models AC2-5A..., AC2-5J..., AC2-5T... only.	
RLO	-19.9...RHI	Minimum range value (in the models AC2-5A..., AC2-5J... only) RLO takes the minimum value measured by the transmitter (i.e. the value matching 0V, 0/4mA).	
RHI	RLO...99.9	Maximum range value (in the models AC2-5A..., AC2-5J... only) RHI takes the maximum value measured by the transmitter (i.e. the value matching 1V, 20mA)	
OS1	-12.5...12.5°	Probe T1 offset.	
TLD	1...30min	Delay for minimum temperature (TLO) and maximum temperature (THI) logging.	
SIM	0...100	Display slowdown	
ADR	1...255	AC1-5 address for PC communication	
PRT	ASC; RTU	ASCII and RTU Modbus protocol selection	

INPUT SPECIFICATIONS

MODEL	INPUT	RANGE [MEASUREMENT ACCURACY]		
		SCL=1°C	SCL=2°C	SCL=°F
AC2-5A...	0+1V	RLO+RHI [± 3 mV]		---
AC2-5I...	INP = 0mA INP = 4mA	RLO+RHI [± 0.2 mA]		---
AC2-5J...	INP=T1 INP=T2	TC "J" TC "K"	-50+750°C [± 3 °C] -50+999°C [± 3 °C]	-60+999°F [± 5 °F]
AC2-5P...	PT100	-50/-19.9+99.9/150°C [± 0.3 °C]	-100+850°C [± 1 °C(-50+850°), ± 2 °C]	-150+999°F [± 2 °F(-60+999°), ± 4 °F]
AC2-5T...	INP=ST1	LAE ST1..	-50/-19.9 + 99.9/150°C [± 0.3 °C(-30+130°), ± 1 °C]	-50 + 150°F [± 0.6 °F(-20+260°), ± 2 °F]
	INP=SN4	LAE SN4..	-40/-19.9 + 99.9/125°C [± 0.3 °C(-40+100°), ± 1 °C]	-40 + 125°F [± 0.6 °F(-40+210°), ± 2 °F]

WIRING DIAGRAMS



TECHNICAL DATA

Power supply
AC2-5...D 12Vdc $\pm 10\%$, 2W
AC2-5...W 110 - 230Vac $\pm 10\%$, 50/60Hz, 2W

Relay outputs (AC2-5.R..)
OUT1 3,6 FLA, 21,6 LRA 240Vac - 12A resistive
OUT2 1 FLA, 6 LRA, 240V - 7A resistive

SSR drive (AC2-5.M..)
OUT1 15mA 12Vdc

Inputs
see table of input specifications

Measurement range
see table of input specifications

Measurement accuracy
see table of input specifications

Operating conditions
-10 ... +50°C, 15%...80% U.R.

CE (Reference Norms)
EN60730-1; EN60730-2-9;
EN50522 (Class B); EN50082-1

Front protection
IP55



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